## A Magnetic Playground for SubRiemannian Geodesics

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Enrico's Int'I sR seminar

via Zoom, April 29, 2020

(*) : am retiring, July 1, 2020:
so - keep me in mind for post
C-virus longish term invites, eg, for 2021..

Two-plane fields in 3-space: $\left\{d z-A_{1}(x, y) d x-A_{2}(x, y) d y=0\right\}$ ‘distribution’, D
one-form, $\theta$
(here: $A_{1} d x+A_{2} d y=y d x$ )

D can be put in this form, provided: the two-planes don't go vertical: $\frac{\partial}{\partial z} \notin D(x, y, z)$
and they are invariant under z-translations

Getting there:
PROBLEM : to join (x_0, y_0, z_0) to (x_1, y_1, z_1) by a horizontal path. `horizontal' $=$ tangent to D .

Write horiz. paths as control system:

$$
\begin{aligned}
& \dot{x}=u_{1} \\
& \dot{y}=u_{2} \\
& \dot{z}=u_{1}(t) A_{1}(x, y)+u_{2}(t) A_{2}(x, y) .
\end{aligned}
$$

or:

$$
\dot{q}=u_{1}(t) X(q(t))+u_{2}(t) Y(q(t))
$$

with:

$$
X=\frac{\partial}{\partial x}+A_{1}(x, y) \frac{\partial}{\partial z}
$$

$$
Y=\frac{\partial}{\partial y}+A_{2}(x, y) \frac{\partial}{\partial z}
$$

## Strategy:

1. Line up $x$ and $y$ coordinates, using a line segment
2. Fiddle around at the final ( $\mathrm{x}_{-} 1, \mathrm{y}_{-} 1$ ) using planar loops c .

Step 1. $u_{-} 1(t)=x \_1-x \_0=$ const ;

$$
u_{-} 2(t)=y_{-} 1-y_{-} 0,
$$

$0<t<1$.
with i.c.: $x(0)=x \_0, y(0)=y \_0, z(0)=z \_0$.
yields: $x(1)=x \_1, y(1)=y \_1$ but

$$
z(1)=\int_{\ell} A_{1} d x+A_{2} d y \neq z_{1}
$$

Step 2. Try moving around ina planar loop c based at (x_1, y_1). Then our height $z$ changes according to:

$$
\dot{z}=A_{1}(x, y) \dot{x}+A_{2}(x, y) \dot{y}
$$

or...

$$
\begin{gathered}
\Delta z=\int_{c} A_{1} d x+A_{2} d y=\iint_{D} B(x, y) d x d y=\begin{array}{l}
\text { Flux of } \\
\text { Magnetic Field }
\end{array} \\
B(x, y)=\frac{\partial A_{2}}{\partial x}-\frac{\partial A_{1}}{\partial y} \\
=\text { Magnetic Field }
\end{gathered}
$$

So, choose c so that flux $=z_{-} 1-z(1)$.

## DONE!

( via Lie brackets: $[\mathrm{X}, \mathrm{Y}]=\mathrm{B}(\mathrm{x}, \mathrm{y}) \mathrm{Z} ; \quad Z=\frac{\partial}{\partial z}$

## Next. Getting there optimally:

Join (x_0, y_0, z_0) to (x_1, y_1, z_1)
by the shortest horizontal path connecting them.
'Shortest?": Let the length of a horiz. path = length of its proj. to xy plane.
(we need that D does not go vertical for this def. to work)

$$
\begin{gathered}
\Longleftrightarrow \ell_{s R}(\gamma)=\ell_{\mathbb{R}^{2}}(c) ; c=\pi \circ \gamma, \pi(x, y, z)=(x, y) \\
\Longleftrightarrow s R \text { struc. is }: D=\left\{d z-A_{1} d x-A_{2} d y=0\right\} \\
\text { and }:\langle\cdot, \cdot\rangle=\left.\left(d x^{2}+d y^{2}\right)\right|_{D} \\
\Longleftrightarrow X=\frac{\partial}{\partial x}+A_{1} \frac{\partial}{\partial z} \quad \text { form an orthonormal frame } \\
, Y=\frac{\partial}{\partial y}+A_{2} \frac{\partial}{\partial z} \quad \text { for D }
\end{gathered}
$$

complete this frame:

$$
Z=\frac{\partial}{\partial z}
$$

Deriving sR geodesics. Use $\theta=d z-A_{1}(x, y) d x-A_{2}(x, y) d y$

Riem. structure ('penalty metric) tending to

$$
d s_{\epsilon}^{2}=d x^{2}+d y^{2}+\frac{1}{\epsilon^{2}} \theta^{2} \quad \rightarrow_{\epsilon \rightarrow 0} \quad \text { our sR structure; }
$$

$$
d x, d y, \theta \quad \leftrightarrow_{d u a l} \quad X, Y, Z
$$

so dually:

$$
\begin{aligned}
& X^{2}+Y^{2}+\epsilon^{2} Z^{2} \rightarrow X^{2}+Y^{2} \quad \text { encodes sR structure. } \\
& \text { viewed as: } \\
& \text {-2nd order diff'। operators } \\
& \text {-co-metric [symm. bilinear form on } T^{\star} \text { ] } \\
& \text {-fiber-quadratic f'n ('Hamiltonian'!) on cotangent bundle }
\end{aligned}
$$

Symbol of $\mathrm{X}:=\mathrm{X}$, thought of as a fiber-linear Hamiltonian on $\mathrm{T}^{*}$

$$
\begin{gathered}
X=\frac{\partial}{\partial x}+A_{1}(x, y) \frac{\partial}{\partial z} \longrightarrow P_{X}=p_{x}+A_{1}(x, y) p_{z} \\
Y=\frac{\partial}{\partial y}+A_{2}(x, y) \frac{\partial}{\partial z} \longrightarrow P_{Y}=p_{y}+A_{2}(x, y) p_{z} \\
Z=\frac{\partial}{\partial z} \quad \longrightarrow P_{Z}=p_{z} \\
\left(x, y, z, p_{x}, p_{y}, p_{z}\right) \text { coord. on } T^{*} \mathbb{R}^{3} \\
\quad p=p_{x} d x+p_{y} d y+p_{z} d z \in T_{(x, y, z)}^{*} \mathbb{R}^{3} \\
H_{\epsilon}=\frac{1}{2}\left(P_{X}^{2}+P_{Y}^{2}+\epsilon^{2} P_{Z}^{2}\right) \rightarrow \frac{1}{2}\left(P_{X}^{2}+P_{Y}^{2}\right) \\
\text { governs (normal) geodesics. }
\end{gathered}
$$

Full disclosure:
__up till now, right out of a review of the book
'A Comprehensive Guide to subRiemannian Geometry'

- by Agrachev, Barilari, and Boscain
which I wrote for the Bulletin of the AMS.
out in a year?

Geod eqns $=$ Ham'ns eqns $=$

$$
\dot{f}=\{f, H\}^{\text {Poisson bracket of fns }}
$$

fruns over fns on $T^{*} ; f=x, y, z, P \_X, P_{-} Y, P \_Z=p \_z$, good enough

$$
\begin{aligned}
\dot{x} & =P_{X} \\
\dot{y} & =P_{Y} \\
\dot{z} & =A_{1} P_{X}+A_{2} P_{Y}+\epsilon \underline{P_{Z}} \\
\dot{P}_{X} & =-\left(B(x, y) \underline{P_{Z}}\right) P_{Y} \\
\dot{P}_{Y} & =+\left(B(x, y) \underline{P_{Z}}\right) P_{X} \quad P_{Z}=\text { const. }=\text { 'charge' } \\
\dot{P}_{Z} & =0
\end{aligned}
$$

Details of computation:

$$
\begin{gathered}
\{f, g h\}=g\{f, h\}+h\{f, g\} \\
\Longrightarrow\left\{f, H_{\epsilon}\right\}=P_{X}\left\{f, P_{X}\right\}+P_{Y}\left\{f, P_{Y}\right\}+\epsilon^{2}\left\{f, P_{Z}\right\} \\
\left\{x, p_{x}\right\}=\left\{y, p_{y}\right\}=\left\{z, p_{z}\right\}=1 ; \quad\{x, y\}=\ldots=0=\left\{p_{x}, p_{y}\right\}=\ldots=0 \\
\Longrightarrow \\
\text { for } f=f(x, y, z),\left\{f, P_{X}\right\}=X[f]:=d f(X) ;\left\{f, P_{Y}\right\}=Y[f] ; . . \\
\Longrightarrow\{f(x, y, z), H\}=P_{X} X[f]+P_{Y} Y[f] \Longrightarrow u_{1}(t)=P_{X}(t), u_{2}(t)=P_{Y}(t) \\
\quad \text { of } \dot{q}=u_{1}(t) X(q(t))+u_{2}(t) Y(q(t))
\end{gathered}
$$

Finally:

$$
\left\{P_{Z}, P_{X}\right\}=\left\{P_{Z}, P_{Y}\right\}=0 ;\left\{P_{X}, P_{Y}\right\}=-B(x, y) P_{Z}
$$

The $x, y, P \_X, P \_Y$ eqns decouple from $z ; P_{\_} Z=\ l a m b d a$, parameter:

$$
\begin{aligned}
& \frac{d}{d t}(x, y)=\left(P_{X}, P_{Y}\right) \\
& \frac{d}{d t}\left(P_{X}, P_{Y}\right)=\lambda B(x, y) \mathbb{J}\left(P_{X}, P_{Y}\right)
\end{aligned}
$$

regardless of \epsilon!
where $\mathbb{J}\left(P_{X}, P_{Y}\right)=\left(-P_{Y}, P_{X}\right)=90$ deg. rotation of (P_X, P_Y)

## These planar ODES

are the eqns of charged particle traveling in the plane under the influence of a magnetic field of strength $B(x, y)$ `pointing out of the plane'

WLOG: $H=1 / 2$, so $\left(P_{-} X\right)^{\wedge} 2+\left(P_{-} Y\right)^{\wedge} 2=1$, which says that the plane curve is parameterizes by arc length s , i.e. $\mathrm{t}=\mathrm{s}$.
Riem case: $P_{X}^{2}+P_{Y}^{2}+\epsilon^{2} P_{Z}^{2}=1 ; P_{Z}=\lambda$
which in turn are equivalent to the geometric eqns:

$$
\kappa(s)=\lambda B(x(s), y(s))
$$

where: $\kappa=$ plane curvature of curve $(x(s), y(s))$
Recall $\kappa$

$$
\vec{q}(s)=(x(s), y(s)), \frac{d}{d s} \vec{q}(s)=\vec{T}(s) ; \frac{d}{d s} \vec{T}(s)=\kappa(s) \mathbb{J} \vec{T}(s)
$$

## Heisenberg Group Case

$B(x, y)=$ const. $=1$
Projected geodesic eqs: $\quad \kappa(s)=\lambda$
Solutions: circles and lines

Geodesics: (rough) helices, and lines
for the circles : rate of climbing

$$
\Delta z / \text { cycle }=(\text { signed }) \text { area of circle }
$$

## GEOMETRIC PHASES

 IN PHYSICS

Alfred Shapere
Frank Wilczek

A nice surprise:

The set of planar curves arising as projections to the xy plane of geodesics is the same for all the Riemannian [penalty] metrics

$$
H_{\epsilon}
$$

and for the sR case

$$
H=\lim _{\epsilon \rightarrow 0} H_{\epsilon}
$$


as charge (\lambda) $->$ infinity normal geod $\mathrm{C}^{\wedge} 0$-converge to abnormal geod


FLAT MARTINET CASE:.

$$
B=x .
$$

Straighten out zero locus:
$B(x, y)=x$;
Martinet model for $\mathrm{D}(\mathrm{x}, \mathrm{y}, \mathrm{z})$ : $d z-\left(x^{\wedge} 2\right) d y=0$

Abnormal geod is also Normal $\lambda_{0} \kappa(s)=\lambda B(x(s), y(s))$ reads ` $0=0$ ' for all choices of multipliers

Other geodesics:
Euler elastica, given by elliptic fns
thank you Levien ; Ardentov


## BRANCHING GEODESICS.

(Meitton-Rizzi, 2019)

$$
B=\left\{\begin{array}{l}
x, y<0 \\
1, y>1
\end{array}\right.
$$

interpolates between
flat Martinet and Heisenberg

A simpler model (for me)

$$
\begin{aligned}
& \quad B=x, y<0 \\
& \text { and } \\
& \quad B(0, y)>0, y>0
\end{aligned}
$$

## sR exponential map

'explanation' of branching

Big open problem:
Are all sR geodesics smooth?

Idea for counterexamples:
look at situations where the zero-locus of $B(x, y)$ is not smooth.

Eg: a) $B(x, y)=x y$ ['normal crossing']


Eero Hakavouri \& Enrico Le Donne shoot down this example. with their "No corners theorem" [2016]
try order 2 contact:

## Eg (b): Tacnode

$$
B=y^{2}-x^{4}
$$


1994. Minnesota. Winter. ICM.

Sussmann. Yacine Chitour.
a certain warm crowded cafe across the railroad tracks. Crossing the frozen
Mississippi, with hexagonal patterns of ice;
(youngest daughter, heart problem appears..)
Agrachev... looking looking looking for counterexamples...

Richard Montgomery [rmont@ucsc.edu](mailto:rmont@ucsc.edu)
Wed, Apr 22, 9:15 PM (7 days ago)
to sussmann, Andrei...
[..] I hope you are well [...]
I have been thinking about old things, and realize that you two have likely already pursued these things and with high likelihood to the bitter end - and found it a dead end. ... Hence this letter, so either I do not repeat your dead end, or you give me some nuggets of hope. [ ....]

Take a magnetic field B whose zero locus is a tacnode or its higher degree generalizations:
$B(x, y)=y^{\wedge} 2-x^{\wedge}\{2 k\}$; Its zero locus -[...] consists of two branches $y=x^{\wedge} k$, and $y=-x^{\wedge} k$
with order $k-1$ of contact at the origin.
[...] Either branch, following until the origin will be a locally minimizing geodesic of Martinet type. So, follow the + branch to the origin, then switch to the other branch.. [to get ] a horizontal curve which is $\left.C^{\wedge} \wedge k-1\right\}$ but not $C \wedge k$.

QUESTION: is this concatenation a minimizer for any positive integer $k$ ?

Sat, Apr 25, 2020 at 3:32 AM Andrei Agrachev wrote:
Dear Richard,
I am fine, thank you very much.
I do not know the answer but may be there is a way to reduce this case to the Hakavuori - Le Donne theorem by taking a jet prolongation in the spirit of your and Misha Monster?

What do you think?
With kindest regards, Andrei

## MEMOIRS <br> of the <br> American Mathematical Society

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## Points and Curves in the Monster Tower

Richard Montgomery Michail Zhitomirskii

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Thm: [Agrachev-M-;][2020]
The tacnode example does not minimize.
More generally any piecewise smooth
(or piecewise $C \wedge k$ )
$s R$ minimizer is smooth $(C \wedge k)$

Pf. By induction ,starting w Hakavouri-LeDonne's $k=1$.

Tool: Prolongation of distributions AND their curves.
Key facts:

1) the sR struc. also prolongs,
2) the prolongation of a geod is a geod.

## Prolonging a distribution

and its horizontal curves
old space: sR manifold $Q$, w distribution D , inner prod on...
new space: points are rays in $D$ downstairs.

$$
\tilde{Q}=\mathbb{P} D
$$


so: points in new space:
(pt, line): $\quad(q, \ell), \ell \subset D(q), q \in Q$
new distribution:
def a): $\tilde{D}(q, \ell)=d \pi_{q}^{-1}(\ell)$
def b): horiz. curves are curves s.t. $(q(t), \ell(t)): d q / d t \in \ell(t)$


Prolonging horizontal curves

$$
q(t) \rightsquigarrow(q(t), \ell(t))=(q(t), \operatorname{span}(d q / d t))
$$

Tacnode case: $\quad x=t, y= \pm t^{2}, z=0 ;$

Prolong: introduce fiber variable u
$\theta$ for fiber

$$
\begin{aligned}
{[d x, d y] } & =[1, u]=[\cos (\theta), \sin (\theta)] \\
u & =\tan (\theta)=d y / d x \\
x=t ; u & =\left\{\begin{array}{l}
2 t, t<0 \\
-2 t, t>0
\end{array} \quad\right. \text { NOW A CORNER! }
\end{aligned}
$$

want to invoke Hakavouri-LeDonne...

Prolonging sR struc.:
use that fiber inherits metric from inner prod on D. Eg: rank 2 case: identify proj line w unit circle [doubled]

X, Y o.n. for D,
o.n. for prolongation of $\mathrm{D} \quad X_{\theta}=\cos (\theta) X+\sin (\theta) Y ; \frac{\partial}{\partial \theta}$

Exer: The proj. map $\pi: \tilde{Q} \rightarrow Q \quad$ is distance decreasing (actually "non-increasing")

Exer: The prolongation of a geodesic is a geodesic.

Proof of theorem: $k=2$ :
Say a geodesic is p.w. $\mathrm{C} \wedge 2$.
Prolong it, and its sR struc.:
Result: a $\mathrm{C}^{\wedge} 1$ geod in the prolongation
WITH corners!
Contradicts `no corners’ theorem of H-LeD.
So the original curve must have been $\mathrm{C} \wedge 2$

General k. Similar. Use induction on k.

## fini. Thank you all , esp. Enrico, for the opportunity to talk and inspiration to prove a theorem

in base
circle radius $r=1 /$ lambda
in space:
roughly, helices:
lie on cylinder of radius,
in sR case: they climb area of circle/ revolution
in Riem case: increase height from sR case by \eps*\lambda per rev.


