

Mumford (Tata Lectures on Theta, II. pp: 3.12-3.13) describes a slick trick to put coordinates at infinity on the standard hyperelliptic curve. We skated the issue earlier. Here I would like to understand this completion. We expressed the surface as $w^2 = p(z)$ where all the roots of p are simple. We will switch to Mumford's notation so s replaces w and t replaces z and $f(t)$ replaces $p(z)$.

The hyperelliptic curve is the subvariety of \mathbb{C}^2 defined by

$$(1) \quad s^2 = f(t)$$

with

$$f(t) = (t - a_1)(t - a_2) \dots (t - a_N)$$

a degree N polynomial whose roots a_i are all distinct. Define the integer k by

$$N = \begin{cases} 2k & \text{for } N \text{ even} \\ N = 2k - 1 & \text{for } N \text{ odd} \end{cases}$$

Then the genus of C_1 is

$$g = k - 1.$$

for the hyperelliptic curve.

We showed on the first day of class that the 'no multiple roots conditions' implies that C_1 is non-singular - i.e. a RS, when viewed as a submanifold of \mathbb{C}^2 . The function t forms a coordinate at points for which $s \neq 0$. In a neighborhood of points with $s = 0$ the function s restricted to C_1 forms a holomorphic coordinate. The issue is how to smoothly compactify C_1 .

I have skated over the issue - really avoiding it.

Here's the slick change of variables I learned from Mumford. Make the change of variables:

$$(2) \quad \tilde{t} = \frac{1}{t}$$

$$(3) \quad \tilde{s} = \frac{s}{t^k}$$

Note that $\tilde{t} = 0$ corresponds to $t = \infty$.

The t change, eq (2) is the standard change to bring infinity to the origin, forming coordinates centered at infinity. The s change is mysterious at first, but we can derive it from the t change. First, partially re-express $f(t)$ in terms of \tilde{t} :

$$(4) \quad f(t) = \prod_i (t - a_i)$$

$$(5) \quad = \prod_i \{t(1 - a_i/t)\}$$

$$(6) \quad = t^N \prod_i \{(1 - a_i \tilde{t})\}$$

Now split up N as either $2k$ or $2k - 1$. In the even case we see that the equation (1) for the curve is equivalent to

$$\left(\frac{s}{t^k}\right)^2 = \prod_i \{(1 - a_i \tilde{t})\}$$

while in the odd case it becomes

$$\left(\frac{s}{t^k}\right)^2 = \frac{1}{t} \prod_i \{(1 - a_i \tilde{t})\}$$

Thus, with \tilde{s} defined as in eq (3) our curve becomes

$$(\tilde{s})^2 = \prod(1 - a_i \tilde{t}), \text{ if } N \text{ even}$$

and

$$(\tilde{s})^2 = \tilde{t}\Pi(1 - a_i\tilde{t}), \text{ if } N \text{ even.}$$

Added points at infinty. To understand the points we've added at infinity by this process, simply set $\tilde{t} = 0$ and solve. In the even case we get $\tilde{s}^2 = 1$, so we have added two points at infinity, $\tilde{s}, \tilde{t} = (\pm 1, 0)$. The curve continues to be 2:1 branched over infinity. In the odd case the equation reads $\tilde{s}^2 = 0$: $\tilde{t} = 0$ or $t = \infty$ is a branch point for the curve— with $(s, t) \mapsto t$ viewed as a map from the curve to the Riemann sphere.

Notation We will call this compactified curve, with points at infinity added the hyper-elliptic curve and denote it by C . When we write $C_1 \subset C$ we mean the affine part sitting inside \mathbb{C}^2 , so C minus its one or two points at infinity.

0.1. A basis for the Abelian differentials. An important theorem asserts that if $g \geq 1$ then the space of global holomorphic one-forms, historically known as “Abelian differentials ” has complex dimension g . One nice thing about hyperelliptic curves is we can write a basis down by hand.

Claim

$$\omega_0 = \frac{dt}{s}, \omega_1 = \frac{tdt}{s}, \dots, \omega_{k-2} = \frac{t^{k-2}dt}{s}$$

form $k - 1 = g$ linearly independent globally holomorphic one-forms on C .

That they are linearly independent is clear, I think. If it is not, try to prove it, by imagining how it could be that $\sum c_i \omega_i = 0$ identically in some neighborhood .

That none of these forms has poles is less clear. It sure looks like $1/s$ has poles when $s = 0$. But $s = 0 \iff f(t) = 0$. We have, from the defining equation, that $2sds = f'(t)dt$ or $\frac{dt}{s} = \frac{2ds}{f'(t)}$. Now, at points where $f(t) = 0$ we must use s as a coordinate instead of t . Also $f'(t) \neq 0$ when $f(t) = 0$, since we've assumed no multiple roots. Re-expressed then our one-form is $\frac{2ds}{f'(t)}$ which is perfectly well defined and has no pole. We have, over points with $t \neq \infty$ both s and t are holomorphic functions on C , and that $t^k \frac{dt}{s}$ are also all holomorphic functions on the affine part $C_1 \subset C$.

It remains to verify that none of these forms have poles at infinity. We switch to the other chart. Thus $t = \frac{1}{\tilde{t}}$ so

$$dt = -\frac{d\tilde{t}}{\tilde{t}^2}$$

while

$$s = t^k \tilde{s} \text{ or } s = \frac{1}{\tilde{t}^k} \tilde{s}$$

It follows that, in the charts at infinity we have

$$\frac{dt}{s} = -\tilde{t}^{k-2} \frac{d\tilde{t}}{\tilde{s}}.$$

Let us do the case of N even. Then there are two points at ∞ corresponding to the two roots $\tilde{s} = \pm 1$ to $(\tilde{s})^2 = \Pi(1 - a_i\tilde{t})$. Neither is zero, so that $d\tilde{t}/\tilde{s}$ has no pole at either. Since $t^\ell = \tilde{t}^{-\ell}$ we have that, expressed near infinity:

$$\omega_\ell = -\tilde{t}^{k-\ell-2} \frac{d\tilde{t}}{\tilde{s}}$$

which has no pole at $\tilde{t} = 0$ as long as $k - \ell - 2 \geq 0$ which is to say, for $\ell = 0, 1, 2, \dots, k - 2$. We have shown that all these ω_ℓ are holomorphic over the entirety of C .

Exercise Do the case $N = 2k - 1$ is odd.

Due to the dimension count and the claim we can state the result as follows: An alternative way to state the claim is that any holomorphic differential (as opposed to a meromorphic differential) on the hyperelliptic curve is of the form $\omega = \frac{R(t)dt}{s}$ where $R(t)$ is a polynomial of degree at most $k - 2$. Note $k - 2 = g - 1$ and the space of such polynomials has dimension g .

Where'd this change of variables at infinity come from? What's it mean? Mumford's magical change of coordinates smelled of weighted projective space. The weighted projective space denoted $\mathbb{P}(1, 1, k)$ is the quotient of $\mathbb{C}^3 \setminus \{0\}$ by the action of \mathbb{C}^* which sends (X, Y, Z) to $(\lambda X, \lambda Y, \lambda^k Z)$. Indeed if we rethink of $f(t)$ as a homogeneous polynomial by setting $f(t_1, t_2) = \Pi_i(t_1 - a_i t_2)$ then

$$s^2 = f(t_1, t_2)$$

is weighted homogeneous of degree $2k$ in $\mathbb{P}(1, 1, k)$. C_1 is obtained by setting $t_2 = 1$ while C_2 is obtained by setting $t_1 = 1$. To work out the change of variables set $[X, Y, Z] = [t, 1, s] = [1, \tilde{t}, \tilde{s}]$ where, as per usual projective space $[X, Y, Z]$ denotes the \mathbb{C}^* orbit through X, Y, Z . The C_1 part is thus in the chart $Y \neq 0$ while the C_2 part is in the chart $X \neq 0$. We first work out t, s . We must have that $t = X/Y, s = Z/Y^k$ we need as coordinates \mathbb{C}^* invariant functions. Similarly we see that $\tilde{t} = Y/Z, \tilde{s} = Z/X^k$. So $\tilde{t} = 1/t$ while $\tilde{s} = Z/(Y^k)(X^k/Y^k) = s/t^k$, explaining Mumford's magical change of coordinates. I found this trick by stumbling about the web, after googling "hyperelliptic curve in weighted homogeneous" and getting the following reference of Miles Reid from the early 1990s: <https://homepages.warwick.ac.uk/~masda/surf/more/grad.pdf> The example is mostly worked out on p. 2. There he writes: ". Note that it is not a wise move to take the projective closure of C_1 in straight $\mathbb{C}\mathbb{P}^2$ - it leads to a complicated singularity at infinity, and general confusion."

Notes on impossibility of embedding in straight $\mathbb{C}\mathbb{P}^2$. This unwise move is **exactly** what most texts seem to do when dealing with the points at infinity on the hyperelliptic curve! The standard trick is to homogenize the polynomial thus defining a compact (irreducible) curve in $\mathbb{C}\mathbb{P}^2$ containing C_1 as its affine part. See Brieskorn-Knorrer, top p. 620, example (5). This yields a (rather deep and non-generic!) singularity at the added point at infinity.

Indeed, there is NO WAY to smoothly embed 'most hyperelliptic curves in $\mathbb{C}\mathbb{P}^2$. A smooth curve in $\mathbb{C}\mathbb{P}^2$ is defined as the zero locus of some homogeneous polynomial in three variables. If d is the degree of the variety then

$$g = \frac{(d-1)(d-2)}{2}$$

This is Lemma 4, p. 611 of Brieskorn-Knorrer and follows fairly simply from the Riemann-Hurwitz. See what B-K call 'Theorem 5' a bit after lemma 4, or see the proof of lemma 4 there. Kirwan is another good source for this.