

1. Let $T \in \mathcal{L}(V^*)$, $v_1, \dots, v_p \in V$ are linearly dependent.

$$\text{Thus, } \exists j \text{ s.t. } v_j = \sum_{\substack{i=1 \\ i \neq j}}^p \alpha_i v_i$$

$$\begin{aligned} \Rightarrow T(v_1, \dots, v_p) &= T(v_1, \dots, \alpha_1 v_1 + \dots + \alpha_p v_p, \dots, v_p) \\ &= \alpha_1 T(v_1, \dots, v_1, \dots, v_p) + \dots + \alpha_p T(v_1, \dots, v_p, \dots, v_p) \text{ by additivity.} \\ &= 0. \end{aligned}$$

2. Suppose $\phi_1, \dots, \phi_r \in V^*$ are linearly dependent, then $\exists j$ s.t. $\phi_j = \alpha_1 \phi_1 + \dots + \alpha_p \phi_p$, j th term omitted.

$$\text{Since } \phi_i \wedge \phi_j = -\phi_j \wedge \phi_i, \phi_i \wedge \phi_i = 0$$

$$\begin{aligned} \text{then } \phi_1 \wedge \dots \wedge (\alpha_1 \phi_1 + \dots + \alpha_p \phi_p) \wedge \dots \wedge \phi_p \\ = \alpha_1 \phi_1 \wedge \dots \wedge \phi_1 \wedge \dots \wedge \phi_p + \dots + \alpha_p \phi_p \wedge \dots \wedge \phi_p \\ = 0. \end{aligned}$$

3. Suppose $\phi_1, \dots, \phi_k \in V^*$, $v_1, \dots, v_k \in V$, $K = \dim V$.

$$\begin{aligned} \phi_1 \wedge \dots \wedge \phi_k &= \text{Alt}(\phi_1 \otimes \dots \otimes \phi_k) \\ &= \frac{1}{k!} \sum_{\sigma \in S_k} \phi_{\sigma(1)} \otimes \dots \otimes \phi_{\sigma(k)} \cdot \text{sgn}(\sigma). \end{aligned}$$

$$\begin{aligned} \phi_1 \wedge \dots \wedge \phi_k(v_1, \dots, v_k) &= \frac{1}{k!} \sum_{\sigma \in S_k} (-1)^{\text{sgn}(\sigma)} \phi_{\sigma(1)} \otimes \dots \otimes \phi_{\sigma(k)}(v_1, \dots, v_k) \\ &= \frac{1}{k!} \sum_{\sigma \in S_k} (-1)^{\text{sgn}(\sigma)} \phi_{\sigma(1)}(v_1) \dots \phi_{\sigma(k)}(v_k). \end{aligned}$$

Define a matrix $M = [\phi_j(v_i)]$

This is the expression of $\det(M)$

$$\Rightarrow \phi_1 \wedge \dots \wedge \phi_k(v_1, \dots, v_k) = \frac{1}{k!} \det[\phi_j(v_i)]$$

4. The proof for 3 is true for all $1 \leq k \leq \dim(V)$, thus, it's proved.

6. Let $T \in \Lambda^k(V^*)$, $\dim V = k$, let $\{v_1, \dots, v_k\}$, $\{v'_1, v'_2, \dots, v'_k\}$ be two ordered basis. Then, $\exists A \in \text{Hom}(V, V)$ s.t. A transform B_1 to B_2 .
 \Rightarrow since B_1, B_2 are equivalently oriented, then $|A| > 0$.

$$\begin{aligned} \text{Consider } T(v'_1, \dots, v'_k) &= T(Av_1, \dots, Av_k) \\ &= A^* T(v_1, \dots, v_k) \\ &= (\det A) T(v_1, \dots, v_k) \text{ by determinant theorem.} \\ &\Rightarrow T(v_1, \dots, v_k), T(v'_1, \dots, v'_k) \text{ have same sign} \end{aligned}$$

\Leftarrow Since $T(v_1, \dots, v_k), T(v'_1, \dots, v'_k)$ have the same sign
 Then $T(v'_1, \dots, v'_k) = \lambda T(v_1, \dots, v_k)$ $\lambda > 0$.

Let A be the transformation matrix from $B_1 \rightarrow B_2$.

$$T(v'_1, \dots, v'_k) = (\det A) T(v_1, \dots, v_k) = \lambda T(v_1, \dots, v_k)$$

$$\Rightarrow \det A = \lambda > 0$$

$\Rightarrow B_1, B_2$ are same oriented.

b) Let V be an oriented vector space. Define a natural orientation of $T \in \Lambda^k(V^*)$ to be the sign of $T(v_1, \dots, v_k)$ for any positively oriented ordered basis $\{v_1, \dots, v_k\}$ for V .

By (a), we prove the sign of $T(v_1, \dots, v_k)$ is independent the choice of $\{v_1, \dots, v_k\}$ when two basis has same orientation.

Thus, define the relation $\sim : T(V_1, \dots, V_n)$'s sign. $\{v_1, \dots, v_n\}$ is positively oriented.

Reflexivity obviously hold.

Symmetry obviously hold.

Transitivity obviously hold.

$\Rightarrow \sim$ is an equivalence relation

\Rightarrow It's a well-defined orientation.

Qx Define the orientation of $\Lambda^k(V^*)$ as follows.

by def.

(c) let $\Lambda^k(V^*)$ be oriented, let $T \in \Lambda^k(V^*)$ $T \neq 0$.

Define an orientation to V as:

let $\{v_1, \dots, v_k\} = B_1$, $\{v'_1, \dots, v'_k\} = B_2$.

if $T(v_1, \dots, v_k) \neq 0$ & $T(v'_1, \dots, v'_k)$ has same sign, then by def, $\{v_1, \dots, v_k\}$, $\{v'_1, \dots, v'_k\}$ are equivalently oriented.

Fix $\{e_1, \dots, e_k\}$ and all ~~the~~ basis equivalently oriented to $\{e_1, \dots, e_k\}$ can be assigned $+1$.
Otherwise -1 .

\Rightarrow It defines a natural orientation on V .

10th let V be an oriented k -dimensional vector subspace of \mathbb{R}^n .

let $T \in \Lambda^k(V^*)$.

let $\{v_1, \dots, v_k\}$, $\{v'_1, \dots, v'_k\}$ be two sets of positively oriented ordered orthonormal bases.

Then $\exists A$ be the transition map.

by 9. A is orthogonal, by 8. $\det(A) = 1$.

by determinant theorem, $A^*T = T$.

So $T(v_1, \dots, v_k) = A^*T(v_1, \dots, v_k) = T(Av_1, \dots, Av_k) = T(v'_1, \dots, v'_k)$.

This proves that, $T \in \Lambda^k(V^*)$ will map positively oriented orthonormal vectors to the same value.

It suffices to show, $\exists T \in \Lambda^k(V^*)$ s.t. $T(v_1, \dots, v_k) = \frac{1}{k!}$.

let ϕ_1, \dots, ϕ_k be the dual vector of v_1, \dots, v_k .

Consider $\phi_1 \wedge \dots \wedge \phi_k = \frac{1}{k!} \sum_{\sigma \in S_k} (-1)^{\text{sgn}(\sigma)} \phi_{\sigma(1)} \otimes \dots \otimes \phi_{\sigma(k)} (v_1, \dots, v_k)$

By part 9, only $i \in S_k$ will give the nonzero value

$$= \frac{1}{k!}$$

T is unique.

Since $\dim \Lambda^k(V^*) = 1$, then T is unique. Since any $T' = \lambda T$

b). already prove in part (a).

F2. let L be a n -dim space. let d be a p -vector, $d \neq 0$. let M_d be the subspace of L consisting of all vectors α satisfying $\alpha \wedge d = 0$.

$$d = \sum \alpha (v_1 \wedge \dots \wedge v_p)$$

as $\dim(M_d) \geq p$, then $\exists v_{p+1} \in M_d$ s.t. v_{p+1} is linearly independent from v_1, \dots, v_p .

Then $\alpha (v_1 \wedge \dots \wedge v_p) \wedge v_{p+1} \neq 0$.

$$\Rightarrow d \neq 0.$$

Contradiction

$$\Rightarrow \dim(M_d) \leq p.$$

\Rightarrow if $\dim(M_d) = p$. let v_1, \dots, v_p be the basis of M_d . Extend v_1, \dots, v_p to a basis of L v_1, \dots, v_n .

then $d = \sum \alpha (v_1 \wedge \dots \wedge v_p)$

$$\sum \alpha (v_1 \wedge \dots \wedge v_p \wedge v_{p+1}) = 0$$

if $d \neq v_1 \wedge \dots \wedge v_p$, then \exists a component

$$v_1 \wedge \dots \wedge v_p \wedge \dots \wedge v_m \quad n \geq m > p$$

thus $\exists v_i \in \{v_1, \dots, v_p\}$ s.t.

$$v_1 \wedge \dots \wedge v_p \wedge \dots \wedge v_m \wedge v_i \neq 0.$$

Contradiction

$$\Rightarrow d = v_1 \wedge \dots \wedge v_p$$

\Leftarrow let $d = v_1 \wedge \dots \wedge v_p$, then $\dim(M_d) \leq p$ by the first part of proof.

but notice that $d \wedge v_i = 0 \quad \forall 1 \leq i \leq p$

$$\Rightarrow \dim(M_d) \geq p$$

$$\Rightarrow \dim(M_d) = p.$$

2. let d be any $(n-1)$ -vector, then $\dim(M_d) \leq n-1$

for 2 cases, $d = d_1 \wedge \dots \wedge \hat{d}_i \wedge \dots \wedge d_n + d_1 \wedge \dots \wedge d_j \wedge \dots \wedge d_n$ $\cdot \# |d_1 \wedge \dots \wedge d_n \wedge (d_i + d_j)|$

\uparrow
omit

d_i, d_j omit

$= d_1 \wedge \dots \wedge d_n \wedge d_k$ \uparrow
redefine as d_k