

The 'arbitrary Hessian' problem

To show: if  $df(p) \neq 0$ .

then by a change of coordinates  
we can insure

$$\frac{\partial^2 f}{\partial x_i \partial x_j}(p)$$

is any symmetric matrix.

Starting point. Normal form for  
functions:  $\exists$  coordinates  $(x^1, \dots, x^n)$   
centered at  $p$  ( $x^i(p) = 0$ )  
s.t. in these coordinates  
 $f(x^1, \dots, x^n) = x^1 + f(p)$

$n=1$ . WLOG  $p=0$ ,  $f(x) = x + c$ .

$$\frac{\partial f}{\partial x} = 1, \quad \frac{\partial^2 f}{\partial x^2} = 0.$$

Change of coordinates

$$y = x + ax^2$$

What is  $\frac{\partial^2 f}{\partial y^2} \Big|_0$  ?

Way 1  $x = y - ax^2 = y - ay^2 + O(y^3)$

But  $f(x) = x + c$

So in terms of  $y$ :

$$f = y - ay^2 + O(y^3)$$

$$\frac{\partial f}{\partial y} = -2ay + O(y^2)$$

$$\frac{\partial^2 f}{\partial y^2} = -2a.$$

$n=1$ . Way 2.

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial x} \frac{dx}{dy}$$

But

$$\frac{\partial f}{\partial x} = 1, \quad \frac{\partial x}{\partial y} = \frac{1}{\frac{dy}{dx}}$$

$$\& \frac{dy}{dx} = \frac{d}{dx}(x+ax^2) = 1+2ax$$

$$\text{So } \frac{dx}{dy} = \frac{1}{1+2ax} = 1-2ax+O(x^2)$$

$$\& \frac{\partial f}{\partial y} = 1 \cdot (1-2ax) + O(x^2)$$

$$\& \frac{\partial^2 f}{\partial y^2} \Big|_{y=0} = -2a$$

$y=0$ . ✓

checks with  
computation, way 1.

General n

Again :  $f = x' + C$  in  $x$ -coordinates

Try

$$y^1 = x^1 + \sum A_{ij} x^i x^j$$

$$y^2 = x^2$$

$$y^3 = x^3$$

$\vdots$

$$y^n = x^n.$$

arbitrary  
symmetric.

Way 1. ~~invert~~ invert coordinate change

$$x^i = y^i - \sum A_{ij} x^i x^j$$

But  $x^i = y^i + O(y^2)$

(for  $i > 1$ ,  $x^i = y^i$ , for  $i=1$ ,  $x^1 = y^1 + O(y^2)$ )

so

$$x^1 = y^1 - \sum_{\text{all } ij} A_{ij} y^i y^j + O(y^3).$$

$$f = x^1 + C = y^1 - \sum A_{ij} y^i y^j + C + O(y^3)$$

$$\frac{\partial f}{\partial y^i} = \delta_i^1 - 2A_{ij} y^j + O(y^2)$$

$$\frac{\partial^2 f}{\partial y^j \partial y^i} = -2A_{ij} + O(y)$$

so  $\frac{\partial^2 f}{\partial y^i \partial y^j} = 0$

$$\frac{\partial^2 f}{\partial y^i \partial y^j} = -2A_{ij} = \text{arbitrary symmetric.}$$

Way 2

$$\frac{\partial f}{\partial y^i} = \frac{\partial f}{\partial x^l} \frac{\partial x^l}{\partial y^i}$$

$$\text{But } \frac{\partial f}{\partial x^l} = \begin{cases} 1, & l=1 \\ 0, & l \neq 1 \end{cases}$$

So

$$\frac{\partial f}{\partial y^i} = \frac{\partial x^1}{\partial y^i}$$

Is the  $1, i$  entry of the Jacobian of the inverse transformation of  $\vec{x} \rightarrow \vec{y}(\vec{x})$ .

$$\text{Now } \frac{\partial \vec{x}}{\partial \vec{y}} = \left( \frac{\partial \vec{y}}{\partial \vec{x}} \right)^{-1}$$

$$y^1 = x^1 + \sum A_{ij} x^i x^j$$

$$y^2 = x^2 +$$

$\vdots$

$$y^n = x^n$$

$$\frac{\partial \vec{y}}{\partial \vec{x}} = \begin{pmatrix} 1 + 2\sum A_{ij} x^j & 2\sum A_{2j} x^j & \dots & \sum A_{nj} x^j \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & \dots & 1 \end{pmatrix}$$

way 2 ctd

Or

$$\frac{\partial \vec{y}}{\partial \vec{x}} = Id + 2h$$

where  $h = h(x)$  is the rank 1 matrix whose first row

$$\vec{h}_1(x) = (2 \sum A_{1j} x^j, 2 \sum A_{2j} x^j, \dots, 2 \sum A_{nj} x^j)$$

Now as  $\vec{x} \rightarrow 0$ ,  $\vec{h} \rightarrow 0$   
& for  $h$  small

$$(I + h)^{-1} = I - h + O(h^2)$$

holds for  $n \times n$  matrices  
(w any  $\mathbb{R}$ -algebra!)

$$\text{Thus: } \frac{\partial \vec{x}}{\partial \vec{y}} = Id - \frac{1}{2} h(x) + O(h(x))^2.$$

& since  $\vec{x} = \vec{y} + O(x^2) = \vec{y} + O(y^2)$   
we have

$$\frac{\partial \vec{x}}{\partial \vec{y}} = Id - h(y)$$

$$\text{or } \frac{\partial x^i}{\partial y^j} = \delta_j^i - 2 \sum A_{jk} y^k$$

way 2 ct'd.

Finally since  $\frac{\partial f}{\partial y^j} = \frac{\partial x^i}{\partial y^j}$

we have

$$\begin{aligned} \frac{\partial^2 f}{\partial y^i \partial y^j} &= \frac{\partial}{\partial y^j} (\delta_i - 2 \sum A_{jk} y^k + O(y^2)) \\ &= -2A_{ij} + O(y). \end{aligned}$$

& at 0:

$$\frac{\partial^2 f}{\partial y^i \partial y^j} = -2A_{ij}.$$

= arbitrary symmetric  
since  $A_{ij}$  is  
arbitrary, symmetric.