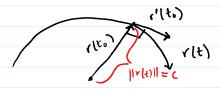
D Let r(t) be a parameterization of a curve. Suppose that ||r(t)|| = c for all  $t \in \mathbb{R}$ . Show that r(t) and r'(t) are orthogonal for all  $t \in \mathbb{R}$ .

The Picture:



Proof We need to show that  $r(t) \cdot r'(t) = 0$ . By assumption, we have  $c^2 = ||r(t)||^2$ 

Thus,  $0 = \frac{d}{dt} c^2 = \frac{d}{dt} ||r(t)||^2 = \frac{d}{dt} (r(t) \cdot r(t))$ 

(x) Product rule for dot product

 $\begin{array}{ccc} (*) & & \\ & & \\ & & \\ & & \end{array}$   $= & 2r(t)r'(t) \cdot$ 

Dividing by 2 yields (lt). r(t) = 0.

Det Given a curve rlt) we can define the unit tayent vector:

 $T(t) = \frac{r'(t)}{||r'(t)||}$ 

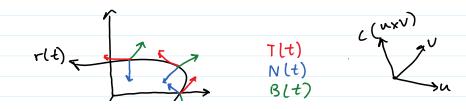
By definition ||T(t)|| = 1 for all tER. By Pooblem 1, we know that T(t) is orthogonal to T'(t). So, we define the Unit

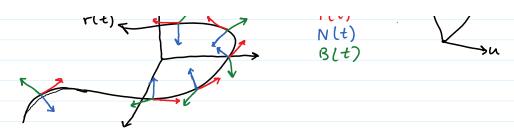
Normal Vector

$$N(t) = \frac{T'(t)}{\|T'(t)\|}$$

Further, we define the Unit Binormal Vector by

Blt) is a unit vector since Tand N we unit vectors.





Note that {Tlt), N(t), B(t)} at each point EER can be obtained from the vectors {i, i, k} via translation and rotation. In linear algebra this is called an orthonormal basis.

The "TNB Frame" is used to describe the geometry of a space curve, such as orientation, curvature, and torsion.

Def Let r(t) be a parameterized space curve and P a point on the curve.

. The Normal plane at P is the polare containing P, N, 3 B.

· The Osculating Plane at P is the plane containing P, T, & N.

Recall	
For a purameterized curve r(t) we ha	Ne
$T(t) = \frac{r'(t)}{  r'(t)  } - unit tangent vector$	
$N(t) = \frac{T'(t)}{1 T'(t)  } - unit normal vector$	, \
B(t) = T(t) × N(t) - unit binormal vecto	r

(2) The helix is given by r(t)= (cost, sint, t). When t= \$\mathbb{T}\_2\$, find:

(a) The Normal plane



(a) By definition, r'(t) is orthogonal to both N(t) and B(t). When t= 17/2,

we have 
$$r(T/2) = (\cos T/2, \sin T/2, T/2) = (0, 1, T/2)$$
 and  $r'(T/2) = (-\sin T/2, \cos T/2, 1)$ 

$$= (-1, 0, 1)$$

So eg. of Nirmal Plane 15:

or equivalently 
$$X-Z=-\frac{\pi}{2}$$
.

R

(5) By definition, the vector B(t) is orthogonal to both T(t) and N(t).

we have: 
$$T(t) = \frac{r'(t)}{|r'(t)|} = \frac{(-\sin t, \cos t, 1)}{\sqrt{2}}$$

$$N(t) = \frac{T'(t)}{||T'(t)||} = \frac{1}{\sqrt{2}} \left( \frac{-\cos t}{\cos t}, -\sinh t, o \right) = \left( -\cos t, -\sinh t, o \right)$$

$$B(t) = T(t) \times N(t) - \begin{vmatrix} i & i & K \\ -siht & cost & 1 \\ + & - & + \\ -cost & -siht & 0 \end{vmatrix}$$

$$= -\cos t \left( \begin{array}{c|c} S & k \\ cost & 1 \end{array} \right) + Sih t \left( \begin{array}{c|c} C & k \\ -sih t & 1 \end{array} \right)$$

So the normal vector is  $B(T/z) = (\sin T/z, -\cos T/z, 1)$  = (1, 0, 1)

So ey of osculating plane is

or equivalently x+2=1/2.

1

Det Let rlt) be a space curve. The curvature of rlt) is given by:

$$K(t) = \frac{\|T'(t)\|}{\|r'(t)\|} = \frac{\|r'(t) \times r''(t)\|}{\|r'(t)\|^3}$$

Note: The equality (x) needs proof, but it is beyond the scope of this exercise.

(3) Show that the curvature of the helix r(t) = (cost, sint, t) is constant,

Solution: We compute: 
$$r'(t) = (-\sin t, \cos t, i)$$
  
 $r''(t) = (-\cos t, -\sin t, o)$ 

$$r'(t) \times r''(t) = \begin{vmatrix} i & 5 & k \\ -siht & c \cdot st & 1 \\ -(sst - siht) & 0 \end{vmatrix}$$

$$= -\cos t \begin{vmatrix} 5 & k \\ \cos t & 1 \end{vmatrix} + \sin t \begin{vmatrix} i & k \\ -\sin t & 1 \end{vmatrix}$$

So , 
$$K(t) = \frac{\|r'(t) \times r''(t)\|}{\|r'(t)\|^3} = \frac{\sqrt{5ih^2(1+cos^2(t+1))}}{\sqrt{5ih^2(1+cos^2(t+1))}} = \frac{\sqrt{2}}{\sqrt{2}} = \frac{1}{2}$$

a) Show that B'(t) \( \tau \) B(t)
b) Show that B'(t) \( \tau \) T(t)

Proof (a) By Problem 1, since ||B(t)||=| for all tElR, we have B(t)·B'(t)=0.

(b) we have

$$B'(t) \cdot T(t) = (T(t) \times N(t))' \cdot T(t)$$

$$= (T'(t) \times N(t) + T(t) \times N'(t)) \cdot T(t)$$

$$= (T'(t) \times N(t)) \cdot T(t) + (T(t) \times N(t)) \cdot T(t)$$

$$= 0 + 0$$

Note that  $T'(t) \times N(t) \cdot T(t) = 0$  since  $T'(t) \times N(t) = T'(t) \times \frac{T'(t)}{\|T'(t)\|} = (0,0,0)$ . Also,  $(T(t) \times N'(t)) \cdot T(t) = 0$  since  $T'(t) \times N'(t) = T'(t) \times \frac{T'(t)}{\|T'(t)\|} = (0,0,0)$ .

By part (a) and (b), we deduce that there is a constant  $C(E) \in \mathbb{R}$  such that  $B'(E) = C(E) (T(E) \times B(E))$  = -C(E) N(E)

The constant Tlt) is called the Torsion, and it describes the degree of twisting that occurs as we traverse rlt).