

1. True/False. You *must* justify your answers.
 - (a) If an isometry of \mathbb{R}^2 cannot be expressed as the composition of less than three reflections, it is a glide reflection.
 - (b) The composition of three reflections across lines through the origin in \mathbb{R}^2 is a reflection.
 - (c) If two lines in the hyperbolic space \mathbb{H} intersect, their images under any Möbius transformation of \mathbb{H} must also intersect.

2. We can define the angle between two lines in spherical geometry as follows: if \mathcal{L}_1 and \mathcal{L}_2 are lines in S^2 (great circles from a Euclidean perspective), let \mathcal{P}_1 and \mathcal{P}_2 denote the planes through the origin in \mathbb{R}^3 such that \mathcal{L}_j is the intersection of \mathcal{P}_j with S^2 , $j = 1, 2$. Let $\tilde{\mathcal{L}}_j$ denote the Euclidean line in \mathcal{P}_j perpendicular to $\mathcal{P}_1 \cap \mathcal{P}_2$. Then the angle between \mathcal{L}_1 and \mathcal{L}_2 is defined to be the angle between $\tilde{\mathcal{L}}_1$ and $\tilde{\mathcal{L}}_2$.
 - (a) Show that for every line \mathcal{L} in S^2 and every point P on \mathcal{L} , there is a unique line \mathcal{L}' in S^2 through P such that the angle between \mathcal{L} and \mathcal{L}' is $\frac{\pi}{2}$. The line is called the perpendicular to \mathcal{L} through P .
 - (b) Given two perpendicular lines \mathcal{L} and \mathcal{L}' as in (a), show that there is a unique line \mathcal{L}'' that is perpendicular to both \mathcal{L} and \mathcal{L}' .
Hint: Visualize the three coordinate planes in \mathbb{R}^3 .

3. Prove the Cauchy-Schwartz inequality $|\mathbf{x}||\mathbf{y}| \geq |\mathbf{x} \cdot \mathbf{y}|$ in \mathbb{R}^2 (the result and proof also holds in \mathbb{R}^n , with the ‘obvious’ Euclidean inner product and distance function on \mathbb{R}^n) by filling in the following outline of a proof:
 - Given two vectors \mathbf{x} and $\mathbf{y} \in \mathbb{R}^2$, define $f : \mathbb{R} \rightarrow [0, \infty)$ by $f(s) := |s\mathbf{x} - \mathbf{y}|^2$.
 - Show that if $\mathbf{x} = 0$, the inequality is trivially satisfied (both sides equal 0).
 - If $\mathbf{x} \neq 0$, compute $f\left(\frac{\mathbf{x} \cdot \mathbf{y}}{|\mathbf{x}|^2}\right)$. Since $f(s) \geq 0$ for all $s \in \mathbb{R}$, conclude that the Cauchy-Schwartz inequality holds in this case as well.

4. Define $f : \mathbb{C} \rightarrow \mathbb{C}$ by $f(z) := \frac{z-i}{z+i}$.
 - (a) Show that f maps the real axis $\{x : x \in \mathbb{R}\}$ onto the unit circle $\{z : |z| = 1\}$ centered at 0.
Hint: Use $\left|\frac{w}{z}\right| = \frac{|w|}{|z|}$ for any $w \in \mathbb{C}$ and nonzero $z \in \mathbb{C}$ and keep in mind that $|x + iy|^2 = x^2 + y^2$ if $x, y \in \mathbb{R}$.
 - (b) Show that f maps $\mathcal{H} = \{x + iy : y > 0\}$ onto the interior $\{z : |z| < 1\}$ of the unit circle centered at 0.
Hint: Don't get buried in algebra. Proceed as directly as possible to a comparison of $(y - 1)^2$ and $(y + 1)^2$ and use the condition that $y > 0$.
 - (c) Show that f does *not* map \mathcal{H} onto \mathcal{H} .

5. Given a unit vector $\mathbf{u} \in \mathbb{R}^2$, define $L : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $L(\mathbf{v}) := \mathbf{v} - (\mathbf{u} \cdot \mathbf{v}) \mathbf{u}$. Show that
- $L^2 = L$, i.e., given any vector $\mathbf{v} \in \mathbb{R}^2$, $L(L(\mathbf{v})) = L(\mathbf{v})$.
 - If \mathbf{v} is in the kernel of L , i.e. $L(\mathbf{v}) = 0$, and \mathbf{w} is in the range of L , i.e. $\mathbf{w} = L(\mathbf{x})$ for some $\mathbf{x} \in \mathbb{R}^2$, then $\mathbf{v} \cdot \mathbf{w} = 0$.
6. Let A, B, C, D be four distinct points in the Euclidean plane such that B and D are on opposite sides of the line AC, $|AB| = |CD|$, and $|AD| = |BC|$. Prove that the line passing through A and B is parallel to the line passing through C and D.
7. Define $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $f(x, y) := (1 - y, 1 + x)$.
- Show that f is a Euclidean isometry.
 - Does f have any fixed points? If so, what are they?
 - Does f preserve or reverse orientation (handedness)?
 - Is f a translation, a reflection, a rotation, or a glide reflection? Justify your answer.
8. (a) Show that if A and B are invertible 2×2 matrices, with associated linear fractional transformations f_A and f_B , then $f_A = f_B$ (in the sense that $f_A(x) = f_B(x)$ for every $x \in \mathbb{R} \cup \{\infty\}$) if and only if A is a rescaling of B , i.e. $A = k B$ for some $k \neq 0$.
- (b) An *equivalence relation* is a binary relation \sim on a set S satisfying
- $a \sim a$ (reflexivity)
 - $a \sim b$ implies $b \sim a$ (symmetry)
 - $a \sim b$ and $b \sim c$ implies $a \sim c$ (transitivity)
- for all a, b and c in S .
- Show that determining the same linear fractional transformation is an equivalence relation on invertible 2×2 real matrices.