

Technical Appendix: Productivity and the role of the global acquisition market

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1 Open Economy - Small Trade Costs - Endogenous A

This section will be identical to the main paper with the exception of allowing A to be determined endogenously. I assume that the conditions of Lemma 3 are satisfied. To summarize:

1. All active firms can export
2. Domestic and foreign acquisitions are not trivially unprofitable relative to the acquisition price.
3. $\frac{(2A-t)t}{4b} - \delta < R_a$

Subject to these conditions, I will rewrite the key equations from the paper. The profits of doing nothing are written as:

$$\pi^{N,STC}(\alpha) = \frac{A^2\alpha k}{2(b\alpha k + v)} - \frac{t(4bA\alpha k - 2b\alpha k t - vt)}{8b(b\alpha k + v)} \quad (1)$$

The profits of buying a domestic firm (B) are:

$$\pi^{B,STC}(\alpha) = \frac{A^2\alpha k}{(2b\alpha k + v)} - \frac{t(8bA\alpha k - 4b\alpha k t - vt)}{8b(2b\alpha k + v)} \quad (2)$$

Finally, the profits from buying a foreign firm (B^*) are:

$$\pi^{B^*}(\alpha) = \pi^{B^*,FT}(\alpha) = \frac{A^2\alpha k}{(2b\alpha k + v)}.$$

Also recall that the incentives to acquire a domestic and foreign firm, respectively, are written as:

$$\begin{aligned} \Delta\Pi(\alpha, A) &= \pi^{B,STC}(\alpha, A) - \pi^{N,STC}(\alpha, A) \\ &= \left(\frac{A^2\alpha v k}{2(b\alpha k + v)(2b\alpha k + v)} \right) + \underbrace{\left(-\frac{tk\alpha(4A-t)}{8(b\alpha k + v)(2b\alpha k + v)} \right)}_{<0} \end{aligned} \quad (3)$$

$$\begin{aligned}
\Delta\Pi^*(\alpha, A) &= \pi^{B^*}(\alpha, A) - \pi^{N,STC}(\alpha, A) - \delta \\
&= \left(\frac{A^2\alpha vk}{2(b\alpha k + v)(2b\alpha k + v)} - \delta \right) + \underbrace{\frac{t(4bA\alpha k - 2b\alpha kt - vt)}{8b(b\alpha k + v)}}_{>0 \text{ for exporters}}
\end{aligned} \tag{4}$$

Using these five functions, I can re-write relevant productivity cutoffs and the corresponding preference conditions over acquisition options. Firms are indifferent between doing nothing and selling at α_S . This cutoff is defined by the following:

$$\pi^{N,STC}(\alpha_S, A) = R_a \tag{5}$$

where,

$$\text{For } \alpha < \alpha_S, S \succ N \tag{6}$$

At $\underline{\alpha}_B$ and $\bar{\alpha}_B$, firms are indifferent between doing nothing and buying domestic capital. Precisely, these cutoffs are defined by the following equations:

$$\Delta\Pi(\underline{\alpha}_B, A) = R_a \tag{7}$$

$$\Delta\Pi(\bar{\alpha}_B, A) = R_a \tag{8}$$

where,

$$\text{For } \alpha \in (\underline{\alpha}_B, \bar{\alpha}_B), B \succ N \tag{9}$$

As was the case under the assumption of free trade, firms within a mid-range of productivity find a domestic acquisition profitable. The existence of $\underline{\alpha}_B$ and $\bar{\alpha}_B$ will be guaranteed by condition 2.

Similarly, defining $\underline{\alpha}_B^*$ and $\bar{\alpha}_B^*$ as the levels of productivity such that firms are indifferent between foreign acquisitions and doing nothing, the indifference between these two options is summarized by the following:

$$\Delta\Pi^*(\underline{\alpha}_B^*, A) = R_a \tag{10}$$

$$\Delta\Pi^*(\bar{\alpha}_B^*, A) = R_a \tag{11}$$

where,

$$\text{For } \alpha \in (\underline{\alpha}_B^*, \bar{\alpha}_B^*), B^* \succ N \tag{12}$$

The existence of two productivity cutoffs, $\underline{\alpha}_B^*$ and $\bar{\alpha}_B^*$, will be guaranteed by conditions 2 and 3.

Finally, for $\frac{(2A-t)t}{4b} > \delta$, the indifference point between foreign acquisitions and domestic acquisitions, α_{BB^*} , is defined as follows:

$$\Delta\Pi(\alpha_{BB^*}, A) - \Delta\Pi^*(\alpha_{BB^*}, A) = 0 \tag{13}$$

$$\alpha_{BB^*} = \frac{v(t^2 + 8\delta b)}{4bk((2A-t)t - 4\delta b)}$$

where,

$$\frac{\partial(\Delta\Pi(\alpha, A) - \Delta\Pi^*(\alpha, A))}{\partial\alpha} = -\frac{vtk(4A-t)}{4(2b\alpha k + v)^2} < 0.$$

Thus,

$$\text{For } \alpha > \alpha_{BB^*}, B^* \succ B. \tag{14}$$

With the incentives for acquisitions in-hand, I now formally define the region over which these incentives are well-defined. Precisely, Lemma 1 defines the region of t and δ that must satisfy OE1-OE4 for any equilibrium A and R_a .

Lemma 1 *There exists a \hat{t} and $\hat{\delta}$ such that, over the space $[0, \hat{t}] \times [0, \hat{\delta}]$, any acquisition stage equilibrium must satisfy conditions one through three..*

Proof. Conditions 1-3 are satisfied by the same conditions as in the main body of the paper. After establishing a simple result that A and R_a are always finite and greater than zero, I will show that there exists a \hat{t} and $\hat{\delta}$ such that over the space $[0, \hat{t}] \times [0, \hat{\delta}]$, any equilibrium must satisfy Conditions 1-3.

The existence of R_a is straightforward. Acquisition demand is decreasing (from positive demand) starting from $R_a = 0$. Eventually, acquisition demand is 0 with R_a high enough. This is since the incentives derived in $\Delta\Pi(\alpha)$ and $\Delta\Pi^*(\alpha)$ are bounded above. The opposite is the case with acquisition supply. For $R_a = 0$, no firms sell. For R_a high enough, all firms sell. Thus, using the intermediate value theorem, there must exist a $R_a > 0$ such that the acquisition market clears. To establish the existence of A , the demand level can be derived from the following:

$$A = \frac{\theta\gamma}{\eta 2M_E (1 - G(\alpha_S(A))) + \gamma} + \frac{\eta 2M_E (1 - G(\alpha_S(A)))}{\eta 2M_E (1 - G(\alpha_S(A))) + \gamma} \bar{p} \quad (15)$$

Defining $\bar{p} = \frac{1}{(1-G(\alpha_S(A)))} \bar{p}_u$, I can rearrange (15) as,

$$\begin{aligned} A(\eta M_E (1 - G(\alpha_S)) + \frac{\gamma}{2}) &= \frac{\theta\gamma}{2} + \eta M_E \bar{p}_u \\ LHS(A) &= RHS(A) \end{aligned} \quad (16)$$

Given preferences, A is bounded between 0 and θ . As $A \rightarrow 0$, this yields the following:

$$\lim_{A \rightarrow 0} A(\eta M_E (1 - G(\alpha_S)) + \frac{\gamma}{2}) = 0 < \frac{\theta\gamma}{2} = \frac{\theta\gamma}{2} + \underbrace{\lim_{A \rightarrow 0} \eta M_E \bar{p}_u}_{=0}$$

As $A \rightarrow \theta$, it is straightforward to show that:

$$\begin{aligned} \lim_{A \rightarrow \theta} A(\eta M_E (1 - G(\alpha_S)) + \gamma) &= \theta \eta M_E (1 - G(\alpha_S)) + \frac{\theta\gamma}{2} \\ &> \frac{\theta\gamma}{2} + \eta M_E \bar{p}_u(\theta) = \frac{\theta\gamma}{2} + \lim_{A \rightarrow \theta} \eta M_E \bar{p}_u \end{aligned}$$

This result follows by showing that $\theta (1 - G(\alpha_S)) > \bar{p}_u(\theta)$. This can be rearranged as $\theta > \bar{p}(\theta)$. Since θ is the maximum price that a firm can charge, the average price $\bar{p}(\theta)$ will be below this level. Thus, given a continuous distribution of productivity, and using the intermediate value theorem, RHS and LHS must cross at least once on the interior, $A \in (0, \theta)$.

Defining the equilibrium values of A and R_a as $A(t, \delta)$ and $R_a(t, \delta)$, I now formally define $[0, \hat{t}] \times [0, \hat{\delta}]$. First, I will define the space $[0, \hat{t}]$ for any δ . Then, over the space $[0, \hat{t}]$, I will define $[0, \hat{\delta}]$.

Step 1: Fix δ . To satisfy condition 3, any region of t must satisfy $\frac{(2A(t, \delta) - t)t}{4b} < R_a(t, \delta)$. Note that $\lim_{t \rightarrow 0} \frac{(2A(t, \delta) - t)t}{4b} = 0$. Since $R_a(t, \delta) > 0$, then there must exist a $t_1(\delta) > 0$ such that

$\frac{(2A(t,\delta)-t)t}{4b} < R_a(t, \delta)$ for $t \in [0, t_1(\delta)]$. Next, regarding domestic acquisitions, condition 2 requires that $\frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 > R_a(t, \delta)$. It is possible that for some t , $\frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 < R_a(t, \delta)$. However, the free trade equilibrium developed in Spearot (2008) dictates that $\frac{(3-2\sqrt{2})}{2b} A^2(0, \delta) > R_a(0, \delta)$. This is convenient, since $\lim_{t \rightarrow 0} \frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 = \frac{(3-2\sqrt{2})}{2b} A(0, \delta)^2$. Thus, there must exist a $t_2(\delta) > 0$ such that $\frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 > R_a(t, \delta)$ holds for $t \in [0, t_2(\delta)]$. Conditions 2 and 3 are jointly satisfied for $t \in [0, \tilde{t}(\delta)]$, where $\tilde{t}(\delta) = \min\{t_1(\delta), t_2(\delta)\} > 0$.

The above paragraph pins down an upper bound $\hat{t}(\delta) > 0$ for each value of δ . Thus, the minimum upper bound of t can be characterized as follows:

$$\hat{t} = \min_{\delta} \{\tilde{t}(\delta)\} > 0$$

Before moving to step two, first note that $\max_{\alpha} \Delta \Pi^*(\alpha|t=0) = \frac{(3-2\sqrt{2})}{2b} A(0, \delta)^2 - \delta$. Since $\frac{\partial \Delta \Pi^*(\alpha)}{\partial t} > 0$ for firms that can export, this implies that $\max_{\alpha} \Delta \Pi^*(\alpha) \geq \max_{\alpha} \Delta \Pi^*(\alpha|t=0)$. Thus, to satisfy foreign-side of condition 2, it is sufficient to show that $\max_{\alpha} \Delta \Pi^*(\alpha) = \frac{(3-2\sqrt{2})}{2b} A(t, \delta)^2 - \delta > R_a(t, \delta)$ is satisfied. This will prove to be a useful relationship to use below.

Step 2: Fix $t \in [0, \hat{t}]$. Over this region of trade costs, $\frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 > R_a(t, \delta)$. Since $\frac{(3-2\sqrt{2})}{2b} A(t, \delta)^2 > \frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2$, this implies that $\frac{(3-2\sqrt{2})}{2b} A(t, \delta)^2 > R_a(t, \delta)$ over this same region. Thus, there must exist a $\tilde{\delta}(t) = \frac{(3-2\sqrt{2})}{8b} (2A(t, \delta) - t)^2 - R_a(t, \delta) > 0$ such that for $\delta \in [0, \tilde{\delta}(t)]$, $\frac{(3-2\sqrt{2})}{2b} A(t, \delta)^2 - \tilde{\delta}(t) > R_a(t, \delta)$. Thus, over the region Thus, the minimum upper bound of δ can be characterized as follows:

$$\hat{\delta} = \min_{t \in [0, \hat{t}]} \{\tilde{\delta}(t)\} > 0$$

Thus, independent of A and R_a , there exists a subspace $[0, \hat{t}] \times [0, \hat{\delta}]$ such that conditions 1-3 are satisfied. This completes the proof. ■

Since we are holding A and R_a fixed, optimal acquisition choice is identical to the main body of the paper. The acquisition market clearing condition is also identical, where in the main body, we are taking A as given. Thus, I now examine and discuss the conditions such that A is uniquely determined, conditional on acquisition choice described in Proposition 1, and the unique R_a characterized in Proposition 2.

Defining $\Theta_N = \underline{\Theta}_N \cup \overline{\Theta}_N$, A is defined by:

$$A = \frac{\theta\gamma}{\eta M + \gamma} + \frac{\eta M}{\eta M + \gamma} \bar{p}(A, \Theta_S, \Theta_N, \Theta_B, \Theta_{B^*}) \quad (17)$$

where,

$$\begin{aligned} \bar{p}(A, \Theta_S, \Theta_N, \Theta_B, \Theta_{B^*}) &= \int_{\alpha \in \Theta_N} \frac{P_N^H(\alpha) + P_N^X(\alpha)}{2(1 - G(\alpha_S))} dG + \int_{\alpha \in \Theta_B} \frac{P_B^H(\alpha) + P_B^X(\alpha)}{2(1 - G(\alpha_S))} dG \\ &+ \int_{\alpha \in \Theta_{B^*}} \frac{P_{B^*}^H(\alpha) + P_{B^*}^X(\alpha)}{2(1 - G(\alpha_S))} dG \end{aligned} \quad (18)$$

and,

$$M = 2M_E (1 - G(\alpha_S(A)))$$

Here, P_N^H and P_B^H are the home price of varieties for firms that acquire nothing and buy domestic capital, respectively. P_N^X and P_B^X are the export prices resulting from these same acquisition outcomes. P^{B*} is the price of varieties for firms that engage in foreign acquisitions. These prices are written as:

$$\begin{aligned} P_N^H &= \frac{2A(b\alpha k + 2v) - vt}{4(b\alpha k + v)}, P_N^X = \frac{2A(b\alpha k + 2v) + 2b\alpha kt + vt}{4(b\alpha k + v)} \\ P_B^H &= \frac{4A(b\alpha k + v) - vt}{4(2b\alpha k + v)}, P_B^X = \frac{4A(b\alpha k + v) + 4b\alpha kt + vt}{4(2b\alpha k + v)} \\ P^{B*} &= \frac{A(b\alpha k + v)}{(2b\alpha k + v)} \end{aligned}$$

Different from the free trade open economy, the productivity cutoffs will not be independent of the demand level, A . This will complicate the analysis of A , where uniqueness will require assumptions over the distribution governing productivity. However, the following lemma summarizes that the existence of A is guaranteed, independent of the productivity distribution.

Lemma 2 *Given optimal acquisition choice and acquisition market clearing, there exists a value \hat{A} that satisfies (17).*

Proof. See proof for lemma 1. ■

The result in Lemma 2 is guaranteed by the intermediate value theorem and the continuous distribution of productivity.

While the existence of \hat{A} is straightforward, uniqueness is not. To guarantee that \hat{A} is unique without additional restrictions on model parameters, an assumption must be placed on the distribution governing productivity. Generally, this assumption can be written as:

D1 For $\alpha \in [\alpha_S, \infty)$, $g(\alpha)$ is "small".

Functionally, the assumption in D1 limits the size of the indirect effects when differentiating (17) with respect to A . Assumption D1 will be satisfied by distributions of productivity that are relatively disperse. For example, an exponential distribution, $g(\alpha) = \lambda e^{-\lambda\alpha}$, with small enough λ will satisfy this assumption. Similarly, a Pareto distribution, $g(\alpha) = h \left(\frac{\tilde{\alpha}^h}{\alpha^{h+1}} \right)$, with small enough h will also satisfy this assumption.¹ Assuming that D1 is satisfied, uniqueness is proven in the following lemma.

Lemma 3 *Given optimal acquisition choice, acquisition market clearing condition, and assuming D1, there exists a unique \hat{A} that satisfies (17).*

Proof. Existence of A is proven in lemma 3. To prove uniqueness, we can rewrite the equation pinning down A as:

$$\begin{aligned} A((1 - G(\alpha_S)) + \frac{\gamma}{2\eta M_E}) &= \frac{\theta\gamma}{2\eta M_E} + \bar{p}_u \\ LHS(A) &= RHS(A) \end{aligned} \tag{19}$$

¹The model can be adapted to allow for a non-binding lower bound of productivity, $\tilde{\alpha}$.

Since by Lemma 1, $LHS(A) < RHS(A)$ at $A = 0$ and $LHS(A) > RHS(A)$ at $A = \theta$, a sufficient condition for uniqueness is that $\frac{\partial LHS(A)}{\partial A} > \frac{\partial RHS(A)}{\partial A}$. I now formalize how D1 ensures this inequality, showing that $\frac{\partial LHS(A)}{\partial A} > \frac{\partial RHS(A)}{\partial A}$ for $t \in [0, \hat{t}]$, using an exponential distribution as an example. Differentiating (19), I can write:

$$\begin{aligned} \frac{\partial LHS(A)}{\partial A} - \frac{\partial RHS(A)}{\partial A} &= 1 - G(\alpha_S) + \frac{\gamma}{2\eta M_E} - g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A - \frac{\partial \bar{p}_u}{\partial A} \\ &= \left(1 - G(\alpha_S) - \frac{\partial \bar{p}_u^{direct}}{\partial A}\right) + \frac{\gamma}{2\eta M_E} - g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A - \frac{\partial \bar{p}_u^{indirect}}{\partial A} \end{aligned}$$

where,

$$\frac{\partial \bar{p}_u}{\partial A} = \frac{\partial \bar{p}_u^{direct}}{\partial A} + \frac{\partial \bar{p}_u^{indirect}}{\partial A}$$

I am splitting up $\frac{\partial \bar{p}_u}{\partial A}$ via Leibniz rule. The term $\frac{\partial \bar{p}_u^{direct}}{\partial A}$ contains the effects of A from inside the integrand. The term $\frac{\partial \bar{p}_u^{indirect}}{\partial A}$ are the effects of A through the limits of integration. To show that $\frac{\partial LHS(A)}{\partial A} - \frac{\partial RHS(A)}{\partial A} > 0$, I will first show that $\left(1 - G(\alpha_S) - \frac{\partial \bar{p}_u^{direct}}{\partial A}\right) > 0$. For $t < \underline{t}(\delta)$, this term can be written as:

$$\begin{aligned} \left(1 - G(\alpha_S) - \frac{\partial \bar{p}_u^{direct}}{\partial A}\right) &= \int_{\alpha_S}^{\alpha_B} \left(1 - \frac{\frac{\partial p_N^H}{\partial A} + \frac{\partial p_N^X}{\partial A}}{2}\right) dG + \int_{\alpha_B}^{\bar{\alpha}_B} \left(1 - \frac{\frac{\partial P_B^H}{\partial A} + \frac{\partial P_B^X}{\partial A}}{2}\right) dG \\ &\quad + \int_{\bar{\alpha}_B}^{\infty} \left(1 - \frac{\frac{\partial p_N^H}{\partial A} + \frac{\partial p_N^X}{\partial A}}{2}\right) dG \\ &> 0 \end{aligned}$$

where $\frac{\partial p_N^H}{\partial A} + \frac{\partial p_N^X}{\partial A} < 2$, $\frac{\partial p_N^H}{\partial A} + \frac{\partial p_N^X}{\partial A} < 2$, and $\frac{\partial p_N^H}{\partial A} + \frac{\partial p_N^X}{\partial A} < 2$ all follow trivially from the fact that $b > 0$ (demand is not perfect elastic). Similar analysis follows for $\underline{t}(\delta) < t < \bar{t}(\delta)$, and $t > \bar{t}(\delta)$. To finish the proof of uniqueness, I need to show that:

$$g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A + \frac{\partial \bar{p}_u^{indirect}}{\partial A} < \left(1 - G(\alpha_S) - \frac{\partial \bar{p}_u^{direct}}{\partial A}\right) + \frac{\gamma}{2\eta M_E}$$

Analytically, this is not possible for all values of t . Thus, I will show how D1 is sufficient for uniqueness. The analysis is similar for all $t \in [0, \hat{t}]$, and I will present the proof for $\underline{t}(\delta) < t < \bar{t}(\delta)$.

For $\underline{t}(\delta) < t < \bar{t}(\delta)$, I can write:

$$g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A + \frac{\partial \bar{p}_u^{indirect}}{\partial A} = (A - (P_N^H(\alpha_S) + P_N^X(\alpha_S))/2) g(\alpha_S) \frac{\partial \alpha_S}{\partial A} \quad (20)$$

$$+ g(\alpha_B) \frac{\partial \alpha_B}{\partial A} (P_N^H(\alpha_B) + P_N^X(\alpha_B) - P_B^H(\alpha_B) - P_B^X(\alpha_B)) / 2 \quad (21)$$

$$+ g(\alpha_{BB^*}) \frac{\partial \alpha_{BB^*}}{\partial A} \left((P_B^H(\alpha_{BB^*}) + P_B^X(\alpha_{BB^*})) / 2 - P^{B^*}(\alpha_{BB^*}) \right)$$

$$+ g(\bar{\alpha}_B^*) \frac{\partial \bar{\alpha}_B^*}{\partial A} \left(P^{B^*}(\bar{\alpha}_B) - P_N^H(\bar{\alpha}_B) - P_N^X(\bar{\alpha}_B) \right) / 2$$

The strategy for uniqueness is to show that $g(\alpha_S) \frac{\partial \alpha_S}{\partial A}$, $g(\underline{\alpha}_B) \frac{\partial \underline{\alpha}_B}{\partial A}$, $g(\alpha_{BB^*}) \frac{\partial \alpha_{BB^*}}{\partial A}$ and $g(\bar{\alpha}_B^*) \frac{\partial \bar{\alpha}_B^*}{\partial A}$ are small enough. If this is the case, uniqueness is proven by ensuring that the term $g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A + \frac{\partial \bar{p}_u^{indirect}}{\partial A}$ is sufficiently small. To derive conditions such that this is the case, I must first solve for $\frac{\partial \alpha_S}{\partial A}$, $\frac{\partial \underline{\alpha}_B}{\partial A}$, $\frac{\partial \bar{\alpha}_B^*}{\partial A}$ and $\frac{\partial \alpha_{BB^*}}{\partial A}$.

It can be shown that $\frac{\partial \alpha_{BB^*}}{\partial A}$ is the only derivative that can be unambiguously signed, as it does not enter into the acquisition market clearing condition. This is written as:

$$\frac{\partial \alpha_{BB^*}}{\partial A} = - \frac{\frac{\partial BB^*(\alpha_{BB^*})}{\partial A}}{\frac{\partial BB^*(\alpha_{BB^*})}{\partial \alpha}} < 0$$

Since prices are lower if a firm avoids trade costs, $((P_B^H(\alpha_{BB^*}) + P_B^X(\alpha_{BB^*}))/2 - P^{B^*}(\alpha_{BB^*})) > 0$. This implies that the term $g(\alpha_{BB^*}) \frac{\partial \alpha_{BB^*}}{\partial A} ((P_B^H(\alpha_{BB^*}) + P_B^X(\alpha_{BB^*}))/2 - P^{B^*}(\alpha_{BB^*}))$ is negative.

The terms $\frac{\partial \alpha_S}{\partial A}$, $\frac{\partial \underline{\alpha}_B}{\partial A}$, $\frac{\partial \bar{\alpha}_B^*}{\partial A}$ are derived using the following:

$$\begin{bmatrix} -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} & 0 \\ -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & 0 & \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \\ g(\alpha_S) & g(\underline{\alpha}_B) & -g(\bar{\alpha}_B^*) \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial \alpha_S}{\partial A} \\ \frac{\partial \underline{\alpha}_B}{\partial A} \\ \frac{\partial \bar{\alpha}_B^*}{\partial A} \end{bmatrix} = \begin{bmatrix} \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} \\ \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} \\ 0 \end{bmatrix}$$

Solving this system of equations, we get:

$$\begin{aligned} \frac{\partial \alpha_S}{\partial A} &= \left(-\frac{1}{D}\right) \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} g(\underline{\alpha}_B) \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A}\right) - \left(-\frac{1}{D}\right) \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\bar{\alpha}_B^*) \underbrace{\left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A}\right)}_{?} \\ &\leq 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial \underline{\alpha}_B}{\partial A} &= \left(-\frac{1}{D}\right) \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) \underbrace{\left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A}\right)}_{?} + \left(-\frac{1}{D}\right) \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A}\right) \\ &\leq 0 \end{aligned}$$

$$\frac{\partial \alpha_{BB^*}}{\partial A} = - \frac{\frac{\partial BB^*(\alpha_{BB^*})}{\partial A}}{\frac{\partial BB^*(\alpha_{BB^*})}{\partial \alpha}} < 0$$

$$\begin{aligned} \frac{\partial \bar{\alpha}_B^*}{\partial A} &= \left(-\frac{1}{D}\right) \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \underbrace{\left(\frac{\partial \Delta \Pi(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B)}{\partial A}\right)}_{?} + \left(-\frac{1}{D}\right) \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\alpha_S) \underbrace{\left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A}\right)}_{?} \\ &\leq 0 \end{aligned}$$

where:

$$\begin{aligned} D &= \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) + \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \\ &< 0 \end{aligned}$$

Writing $g(\alpha_S) \frac{\partial \alpha_S}{\partial A}$:

$$g(\alpha_S) \frac{\partial \alpha_S}{\partial A} = \frac{g(\alpha_S)g(\underline{\alpha}_B) \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B)} + \frac{g(\alpha_S)g(\bar{\alpha}_B^*) \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B)} \quad (22)$$

Generally, as $g(\alpha)$ becomes small for all productivity cutoffs, the numerator of (22) will approach zero faster than the denominator of (22). This is also the case for $g(\underline{\alpha}_B) \frac{\partial \alpha_B}{\partial A}$ and $g(\bar{\alpha}_B^*) \frac{\partial \bar{\alpha}_B^*}{\partial A}$. As a concrete example, consider the exponential distribution, where $g(\alpha) = \lambda e^{-\lambda \alpha}$. Defining $\tilde{g}(\alpha) = e^{-\lambda \alpha}$, I can write (22) as:

$$g(\alpha_S) \frac{\partial \alpha_S}{\partial A} = \frac{\lambda \tilde{g}(\alpha_S) \tilde{g}(\underline{\alpha}_B) \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} + \frac{\lambda \tilde{g}(\alpha_S) \tilde{g}(\bar{\alpha}_B^*) \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} \quad (23)$$

Noting that $\lim_{\lambda \rightarrow 0} \tilde{g}(\alpha) = 1$ for all α , it is immediate that $\lim_{\lambda \rightarrow 0} \left(g(\alpha_S) \frac{\partial \alpha_S}{\partial A} \right) = 0$. I can write similar expressions for $g(\underline{\alpha}_B) \frac{\partial \alpha_B}{\partial A}$, $g(\bar{\alpha}_B^*) \frac{\partial \bar{\alpha}_B^*}{\partial A}$ and $g(\alpha_{BB^*}) \frac{\partial \alpha_{BB^*}}{\partial A}$:

$$g(\underline{\alpha}_B) \frac{\partial \alpha_B}{\partial A} = \frac{\lambda \tilde{g}(\underline{\alpha}_B) \tilde{g}(\bar{\alpha}_B^*) \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} + \frac{\lambda \tilde{g}(\underline{\alpha}_B) \tilde{g}(\alpha_S) \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \left(\frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} \quad (24)$$

$$g(\bar{\alpha}_B^*) \frac{\partial \alpha_{BB^*}}{\partial A} = -\lambda \tilde{g}(\alpha_{BB^*}) \frac{\frac{\partial \alpha_{BB^*}}{\partial A}}{\frac{\partial \alpha_{BB^*}}{\partial \alpha}} \quad (25)$$

$$g(\alpha_{BB^*}) \frac{\partial \bar{\alpha}_B^*}{\partial A} = \frac{\lambda \tilde{g}(\bar{\alpha}_B^*) \tilde{g}(\underline{\alpha}_B) \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \left(\frac{\partial \Delta \Pi(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} + \frac{\lambda \tilde{g}(\bar{\alpha}_B^*) \tilde{g}(\alpha_S) \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right)}{-\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \tilde{g}(\alpha_S) + \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\bar{\alpha}_B^*) - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} \tilde{g}(\underline{\alpha}_B)} \quad (26)$$

Clearly, $g(\underline{\alpha}_B) \frac{\partial \alpha_B}{\partial A}$, $g(\bar{\alpha}_B^*) \frac{\partial \bar{\alpha}_B^*}{\partial A}$ and $g(\alpha_{BB^*}) \frac{\partial \alpha_{BB^*}}{\partial A}$ all approach zero as $\lambda \rightarrow 0$.

Using (23), (24), (25) and (26), it is immediate that $\lim_{\lambda \rightarrow 0} \left(g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A + \frac{\partial \bar{p}_u^{indirect}}{\partial A} \right) < 0$. Thus, there must exist a λ small enough such that,

$$g(\alpha_S) \frac{\partial \alpha_S}{\partial A} A + \frac{\partial \bar{p}_u^{indirect}}{\partial A} < \left(1 - G(\alpha_S) - \frac{\partial \bar{p}_u^{direct}}{\partial A} \right) + \frac{\gamma}{2\eta M_E}$$

which guarantees a unique equilibrium A . This analysis can also extend to a Pareto distribution, provided the that lower bound on productivity is not binding. ■

Free Entry

To close the open economy equilibrium, I now define the free entry condition. After imposing the acquisition market clearing condition, the free entry condition is written as follows:

$$\int_{\alpha \in \Theta_N} \pi^N(\alpha) dG(\alpha) + \int_{\alpha \in \Theta_B} \pi^B(\alpha) dG(\alpha) + \int_{\alpha \in \Theta_{B^*}} \left(\pi^{B^*}(\alpha) - \delta \right) dG(\alpha) = F_E \quad (27)$$

With D1, it is guaranteed that additional entry lowers the ex-ante profitability for all entrants. Thus, provided that the fixed cost of entry is not prohibitively high, there will exist a unique number of entering firms.

1.1 Proof of Proposition 3

$t < \underline{t}(\delta)$

When differentiating any free entry condition with respect to t , the envelope theorem will eliminate any indirect effects through changes in our productivity cutoffs. Differentiating (27) with respect to t , we get:

$$\frac{\partial A}{\partial t} = - \frac{\left(\int_{\alpha_S}^{\alpha_B} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) + 2 \int_{\bar{\alpha}_B}^{\alpha_B} \frac{\partial \pi^{B,STC}(\alpha)}{\partial t} dG(\alpha) + \int_{\bar{\alpha}_B}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) \right)}{\left(\int_{\alpha_S}^{\alpha_B} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) + 2 \int_{\bar{\alpha}_B}^{\alpha_B} \frac{\partial \pi^{B,STC}(\alpha)}{\partial A} dG(\alpha) + \int_{\bar{\alpha}_B}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) \right)} < 1$$

where this derivative is less than one via $\frac{\partial \pi^{j,STC}(\alpha)}{\partial A} > -\frac{\partial \pi^{j,STC}(\alpha)}{\partial t} > 0$ for all acquisition outcomes j .

Differentiating the equilibrium conditions in (5), (8), (7), (27), and the acquisition market clearing condition for $t < \underline{t}(\delta)$, we get:

$$\begin{bmatrix} \frac{\partial \Delta \Pi(\alpha_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & \frac{\partial \Delta \Pi(\alpha_B)}{\partial \alpha} & 0 \\ \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & 0 & \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial \alpha} \\ \frac{\partial E \pi}{\partial A} & 0 & 0 & 0 \\ 0 & g(\alpha_S) & g(\alpha_B) & -g(\bar{\alpha}_B) \end{bmatrix} \begin{bmatrix} \frac{\partial A}{\partial t} \\ \frac{\partial \alpha_S}{\partial t} \\ \frac{\partial \alpha_B}{\partial t} \\ \frac{\partial \bar{\alpha}_B}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\alpha_B)}{\partial t} \\ \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial t} \\ -\frac{\partial E \pi}{\partial t} \\ 0 \end{bmatrix}$$

noting that,

$$\begin{aligned} \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\alpha_B)}{\partial A} &= \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial A} = -\frac{t^2}{2bk(2A-t)} \\ \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\alpha_B)}{\partial t} &= \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial t} = \frac{At}{2bk(2A-t)} \end{aligned}$$

which yields,

$$\frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} > \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} > \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi(\alpha_S)}{\partial A} \right)$$

and

$$\frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial t} > \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial A} > \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi(\alpha_S)}{\partial A} \right)$$

we can solve the system of equations and get:

$$\begin{aligned} \frac{\partial \alpha_S}{\partial t} &= \left(\frac{1}{D} \right) \left(\overbrace{-\frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial \alpha} g(\underline{\alpha}_B)}^+ + \overbrace{\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\bar{\alpha}_B)}^+ \right) \left(\frac{\partial \pi(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi(\alpha_S)}{\partial A} \right) \right) \\ &< 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial \underline{\alpha}_B}{\partial t} &= \left(\frac{1}{D} \right) \left(\overbrace{\frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial \alpha} g(\alpha_S)}^- \right) \left(\frac{\partial \pi(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi(\alpha_S)}{\partial A} \right) \right) \\ &> 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial \bar{\alpha}_B}{\partial t} &= \left(\frac{1}{D} \right) \left(\overbrace{\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\alpha_S)}^+ \right) \left(\frac{\partial \pi(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi(\alpha_S)}{\partial A} \right) \right) \\ &< 0 \end{aligned}$$

where:

$$\begin{aligned} D &= \overbrace{\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\alpha_S)}^+ \overbrace{\frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial \alpha}}^- - \overbrace{\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha}}^+ \overbrace{\frac{\partial \pi^N(\alpha_S)}{\partial \alpha}}^+ g(\bar{\alpha}_B) + \overbrace{\frac{\partial \Delta \Pi(\bar{\alpha}_B)}{\partial \alpha}}^- \overbrace{\frac{\partial \pi^N(\alpha_S)}{\partial \alpha}}^+ g(\underline{\alpha}_B) \\ &< 0 \end{aligned}$$

1.2 Proof of Proposition 4

$\underline{t}(\delta) < t < \bar{t}(\delta)$

Similar to above, I can write $\frac{\partial A}{\partial t}$ as:

$$\frac{\partial A}{\partial t} = - \frac{\left(\int_{\underline{\alpha}_B}^{\underline{\alpha}_S} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) + 2 \int_{\underline{\alpha}_B}^{\alpha_{BB}^*} \frac{\partial \pi^{B,STC}(\alpha)}{\partial t} dG(\alpha) + \int_{\bar{\alpha}_B^*}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) \right)}{\left(\int_{\underline{\alpha}_B}^{\underline{\alpha}_S} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) + 2 \int_{\underline{\alpha}_B}^{\alpha_{BB}^*} \frac{\partial \pi^{B,STC}(\alpha)}{\partial A} dG(\alpha) + \int_{\bar{\alpha}_B^*}^{\infty} \frac{\partial \pi^{F,STC}(\alpha)}{\partial A} dG(\alpha) + \int_{\bar{\alpha}_B^*}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) \right)} < 1$$

where this derivative is less than zero via $\frac{\partial \pi^{j,STC}(\alpha)}{\partial A} > -\frac{\partial \pi^{j,STC}(\alpha)}{\partial t}$ for all acquisition outcomes j .

Differentiating the equilibrium conditions in (5), (11), (7), (27), and the acquisition market clearing condition for $\underline{t}(\delta) < t < \bar{t}(\delta)$, we get:

$$\begin{bmatrix} \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} & 0 \\ \frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & 0 & \frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial \alpha} \\ \frac{\partial E\pi}{\partial A} & 0 & 0 & 0 \\ 0 & g(\alpha_S) & g(\underline{\alpha}_B) & -g(\bar{\alpha}_B) \end{bmatrix} \begin{bmatrix} \frac{\partial A}{\partial t} \\ \frac{\partial \alpha_S}{\partial t} \\ \frac{\partial \underline{\alpha}_B}{\partial t} \\ \frac{\partial \bar{\alpha}_B}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} \\ \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial t} \\ -\frac{\partial E\pi}{\partial t} \\ 0 \end{bmatrix}$$

Continuing, we can write:

$$\begin{aligned} \frac{\partial \alpha_S}{\partial t} &= -\frac{1}{D} \overbrace{\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\bar{\alpha}_B)}^{>0} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right) \\ &\quad - \frac{1}{D} \overbrace{\frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial \alpha} g(\underline{\alpha}_B)}^{<0} \left(\frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right) \\ &\leq 0 \\ \\ \frac{\partial \underline{\alpha}_B}{\partial t} &= -\frac{1}{D} \overbrace{\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B)}^{>0 \text{ (see below)}} \left(\frac{\partial \Delta \Pi^+(\bar{\alpha}_B)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^+(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right) \\ &\quad - \frac{1}{D} \left(\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B) - \frac{\partial \Delta \Pi^-(\bar{\alpha}_B)}{\partial \alpha} g(\alpha_S) \right) \overbrace{\left(\frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &> 0 \\ \\ \frac{\partial \bar{\alpha}_B}{\partial t} &= -\frac{1}{D} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \overbrace{\left(\frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} - \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &\quad - \frac{1}{D} \overbrace{\left(\frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} g(\alpha_S) + \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \right)}^{>0} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) \right) \\ &> 0 \end{aligned}$$

where:

$$\begin{aligned} D &= \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial \alpha} g(\alpha_S) - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B) + \frac{\partial \Delta \Pi^*(\bar{\alpha}_B)}{\partial \alpha} \frac{\partial \pi^N(\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \\ &< 0 \end{aligned}$$

and,

$$\begin{aligned} \frac{\partial \pi^N(\alpha_S)}{\partial A} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial A} &= -\frac{t^2}{2bk(2A-t)} \\ \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi(\underline{\alpha}_B)}{\partial t} &= \frac{At}{2bk(2A-t)} \end{aligned}$$

The sign of $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right)$ is not totally straightforward. While it is clear that $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} > 0$, the sign of $\left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right)$ is ambiguous. However, since $\frac{\partial A}{\partial t} \in (0, 1)$, if we can show that $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) > 0$, it must be the case that $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) > 0$. As a function of model parameters, we can write:

$$\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) = \frac{(A-t)(2(A-t)b\bar{\alpha}_B^*k - vt)}{(2b\bar{\alpha}_B^*k + v)(2A-t)} + \frac{2\delta}{(2A-t)}$$

Since $(2(A-t)b\bar{\alpha}_B^*k - vt) > 0$ for firms that are exporters, and $t < A$ for any export status to occur, it is clear that $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) > 0$. Thus,

$$\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N(\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} \right) > 0$$

Finally, differentiating (13),

$$\frac{\partial \alpha_{BB^*}}{\partial t} = - \frac{\overbrace{\left(\frac{\partial \Delta \Pi^*(\alpha_{BB^*})}{\partial A} - \frac{\partial \Delta \Pi(\alpha_{BB^*})}{\partial A} \right) \frac{\partial A}{\partial t}}^{>0}}{\underbrace{\left(\frac{\partial \Delta \Pi^*(\alpha_{BB^*})}{\partial \alpha} - \frac{\partial \Delta \Pi(\alpha_{BB^*})}{\partial \alpha} \right)}_{>0}} < 0$$

1.3 Proof of Proposition 5

$\bar{t}(\delta) < t$

Virtually identical to above, we can write $\frac{\partial A}{\partial t}$ as:

$$\frac{\partial A}{\partial t} = - \frac{\left(\int_{\alpha_S}^{\alpha_B} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) + \int_{\alpha_B^*}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial t} dG(\alpha) \right)}{\left(\int_{\alpha_S}^{\alpha_B} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) + \int_{\alpha_B^*}^{\alpha_B} \frac{\partial \pi^{F,STC}(\alpha)}{\partial A} dG(\alpha) + \int_{\alpha_B^*}^{\infty} \frac{\partial \pi^{N,STC}(\alpha)}{\partial A} dG(\alpha) \right)} < 1$$

where this derivative is less than zero via $\frac{\partial \pi^{j,STC}(\alpha)}{\partial A} > -\frac{\partial \pi^{j,STC}(\alpha)}{\partial t}$ for all acquisition outcomes j .

Differentiating the equilibrium conditions in (5), (11), (10), (27), and the acquisition market clearing condition for $\bar{t}(\delta) < t$, we get:

$$\begin{bmatrix} \frac{\partial \Delta \Pi^*(\alpha_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & \frac{\partial \Delta \Pi^*(\alpha_B^*)}{\partial \alpha} & 0 \\ \frac{\partial \Delta \Pi^*(\alpha_B^*)}{\partial A} - \frac{\partial \pi^N(\alpha_S)}{\partial A} & -\frac{\partial \pi^N(\alpha_S)}{\partial \alpha} & 0 & \frac{\partial \Delta \Pi^*(\alpha_B^*)}{\partial \alpha} \\ \frac{\partial E\pi}{\partial A} & 0 & 0 & 0 \\ 0 & g(\alpha_S) & g(\alpha_B^*) & -g(\bar{\alpha}_B^*) \end{bmatrix} \begin{bmatrix} \frac{\partial A}{\partial t} \\ \frac{\partial \alpha_S}{\partial t} \\ \frac{\partial \alpha_B^*}{\partial t} \\ \frac{\partial \bar{\alpha}_B^*}{\partial t} \end{bmatrix} = \begin{bmatrix} \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi^*(\alpha_B)}{\partial t} \\ \frac{\partial \pi^N(\alpha_S)}{\partial t} - \frac{\partial \Delta \Pi^*(\alpha_B^*)}{\partial t} \\ -\frac{\partial E\pi}{\partial t} \\ 0 \end{bmatrix}$$

Continuing, we can write (for signs of each term, see below):

$$\begin{aligned} \frac{\partial \alpha_S}{\partial t} &= -\frac{1}{D} \overbrace{\left(-\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial \alpha} \right) g(\underline{\alpha}_B^*) \left(\frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &\quad - \frac{1}{D} \overbrace{\frac{\partial \Delta \Pi (\underline{\alpha}_B)}{\partial \alpha} g(\bar{\alpha}_B^*) \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &> 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial \alpha_B^*}{\partial t} &= \frac{1}{D} \overbrace{\left(-\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) \right) \left(\frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &\quad - \frac{1}{D} \overbrace{\frac{\partial \pi^N (\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} \right) \right)}^{>0} \\ &\leq 0 \end{aligned}$$

$$\begin{aligned} \frac{\partial \bar{\alpha}_B^*}{\partial t} &= -\frac{1}{D} \overbrace{\frac{\partial \Delta \Pi (\underline{\alpha}_B)}{\partial \alpha} g(\alpha_S) \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) \right)}^{>0} \\ &\quad - \frac{1}{D} \overbrace{\frac{\partial \pi^N (\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} \right) \right)}^{>0} \\ &> 0 \end{aligned}$$

where:

$$\begin{aligned} D &= \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial \alpha} \frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial \alpha} g(\alpha_S) - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N (\alpha_S)}{\partial \alpha} g(\bar{\alpha}_B^*) + \frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial \alpha} \frac{\partial \pi^N (\alpha_S)}{\partial \alpha} g(\underline{\alpha}_B) \\ &< 0 \end{aligned}$$

By similar work to above, I can show:

$$\begin{aligned} \frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) &> 0 \\ \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} - \frac{\partial \pi^N (\alpha_S)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} - \frac{\partial \pi^N (\alpha_S)}{\partial A} \right) &> 0 \end{aligned}$$

Finally, I must sign $\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} \right)$. First, I will establish that $\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial t} > 0$ and $\frac{\partial \Delta \Pi^* (\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^* (\underline{\alpha}_B^*)}{\partial A} < 0$. For any value of α , $\frac{\partial \Delta \Pi^* (\alpha)}{\partial t}$ and $\frac{\partial \Delta \Pi^* (\alpha)}{\partial A}$

are written as:

$$\begin{aligned}\frac{\partial \Delta \Pi^*(\alpha)}{\partial t} &= \frac{(2bA\alpha k - 2b\alpha kt - vt)}{4b(b\alpha k + v)} > 0 \text{ (for exporters)} \\ \frac{\partial \Delta \Pi^*(\alpha)}{\partial A} &= \frac{\alpha k(2Av + 2b\alpha kt + vt)}{2(b\alpha k + v)(2b\alpha k + v)} > 0\end{aligned}$$

To sign $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} > 0$ and $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} < 0$, I also need to define $\underline{\alpha}_B^*(\bar{\alpha}_B^*)$:

$$\underline{\alpha}_B^*(\bar{\alpha}_B^*) = \frac{v(8tbAk\bar{\alpha}_B^* - 2bkt^2\bar{\alpha}_B^* + 4A^2v + 4tAv - t^2v)}{2bk(4A^2\bar{\alpha}_B^*kb + 2bkt^2\bar{\alpha}_B^* - 8tbAk\bar{\alpha}_B^* + t^2v - 4tAv)}$$

With $\underline{\alpha}_B^*(\bar{\alpha}_B^*)$, I can write:

$$\begin{aligned}\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} &= -\frac{(8A^2b^2\bar{\alpha}_B^{*2}k^2 - 4A^2v^2 - 16tb^2A\bar{\alpha}_B^{*2}k^2 - 16tbA\bar{\alpha}_B^*kv)t}{4A(2A-t)(2b\bar{\alpha}_B^*k+v)b(b\bar{\alpha}_B^*k+v)} \\ &\quad - \frac{(4b^2\bar{\alpha}_B^{*2}k^2t^2 + 4b\bar{\alpha}_B^*kt^2v + v^2t^2 - 4tAv^2)t}{4A(2A-t)(2b\bar{\alpha}_B^*k+v)b(b\bar{\alpha}_B^*k+v)} \\ \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} &= -\frac{A}{t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} \right)\end{aligned}$$

Since $A > t$, then

$$\left| \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} \right| > \left| \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} \right|$$

Also,

$$\text{sign} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} \right) = -\text{sign} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} \right)$$

Thus, since $\frac{\partial A}{\partial t} \in (0, 1)$, if $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} < 0$, then we can sign the derivative in question. Continuing, $\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} < 0$ if

$$\bar{\alpha}_B^* > \frac{\sqrt{2}v(2A+t+\sqrt{2}t)}{2b(2A-2t-\sqrt{2}t)k}$$

In Lemma 2, I establish that this condition holds, as the maximum of $\Delta \Pi^*(\alpha)$ is indeed $\frac{\sqrt{2}v(2A+t+\sqrt{2}t)}{2b(2A-2t-\sqrt{2}t)k}$. Thus,

$$\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} < 0, \quad \frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} > 0$$

and,

$$\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial t} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial t} + \frac{\partial A}{\partial t} \left(\frac{\partial \Delta \Pi^*(\bar{\alpha}_B^*)}{\partial A} - \frac{\partial \Delta \Pi^*(\underline{\alpha}_B^*)}{\partial A} \right) > 0.$$